



# An introduction to advanced turbulence modelling.

Sébastien DECK

*Applied Aerodynamics Department*

*[sebastien.deck@onera.fr](mailto:sebastien.deck@onera.fr)*



return on innovation

Paris XI –Turbulence

# Unsteadiness in aerodynamics

- RANS/URANS massively used in design (optimization, uncertainties) and for multidisciplinary coupling (flight mechanics, optics, ...)
- When the three-dimensional turbulent unsteady field is required...



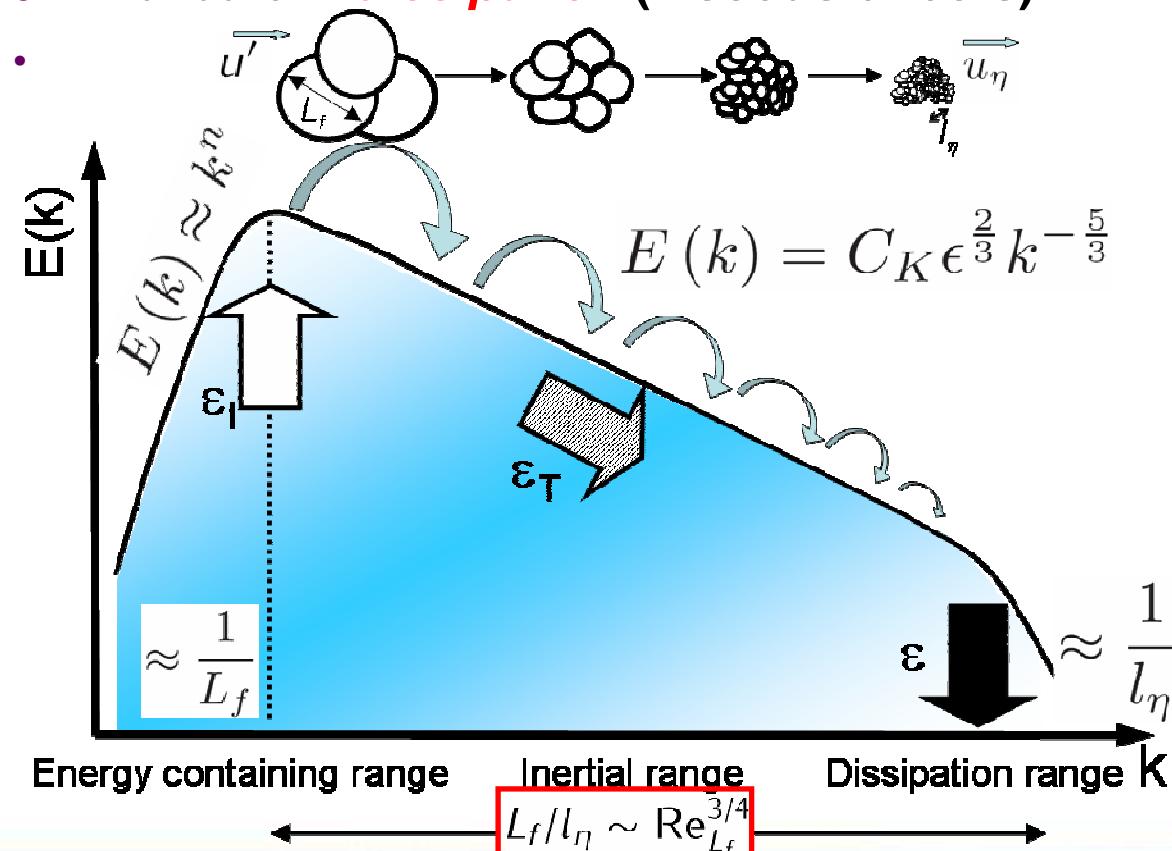
→ Acoustic environment



→ dynamic loads

# Direct Numerical Simulation

- DNS concept: “capture” all active scales
  1. Turbulence **production** (instabilities, ...)
  2. Inter scale energy **transfer** (Kinetic Energy Cascade)
  3. Turbulent **dissipation** (viscous effects)



HIT TKE spectrum

$$\bar{k} = \int_0^{\infty} E(k) dk$$

# Direct Numerical Simulation. Cont'd



- DNS concept: “capture” all active scales
  - 1. Turbulence **production** (instabilities, ...)
  - 2. Inter scale energy **transfer** (Kinetic Energy Cascade)
  - 3. Turbulent **dissipation** (viscous effects)

$$\text{computing time} \propto N_{xyz}.N_t \propto \tilde{C} \cdot \text{Re}_L^3$$

[μs/point/itération]

- at the wall:  $\Delta x \sim l_\eta \sim w.u. \sim 10^{-6}m$
- $L \sim 50m$ ,  $S_{\text{wing}} \approx 1 \text{ m}^2/\text{pax} \approx 10^{12} \text{ w.u.}^2/\text{pax}$
- $(\Delta x^+ \Delta z^+)_{\text{DNS}} \approx 100 \text{ w.u.}^2$   $z$ : spanwise direction
- $N_{xyz} > 10^{16}$  (2080, Spalart et al.)
- is it necessary ?
- need for a compromise between resolved physics/CPU cost

# Contents

- Scale separation. Basics of RANS and LES.
- Hybrid RANS LES approaches
- An introduction to massive calculation
- Applications

# Mode reduction

- **Key idea:** cost reduction = small scale elimination
- **Therefore:**
  - Need for a scale separation operator
  - Resolved scales and unresolved scales
  - Model for resolved/unresolved scale interactions
- **Families of operators**
  - Statistical average → RANS
  - Small scale elimination → LES
  - Combination → Hybrid RANS/LES

# Scale separation

$$f(\mathbf{x}, t) \quad \mathbf{x} = (x_1, x_2, x_3)^T$$

$\mathcal{F}$ : scale separation operator

$$f = \bar{f} + f'$$

$\bar{f} = \mathcal{F}(f)$

$f' = (Id - \mathcal{F})(f)$

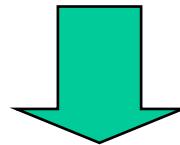
Resolved part of  $f$

Unresolved part of  $f$

This decomposition will be applied to the aerodynamic variables  
Such as the velocity field  $\mathbf{u}$  or the pressure  $P$

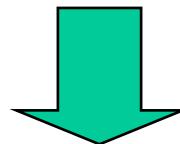
## Scale separation. Cont'd

Global idea of all cost reduction approaches → consider only the resolved field  $\bar{f}$



Introduction of a mathematical closure to account for the unresolved field

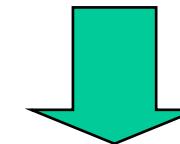
$f'$



$$NS(\bar{f})$$

looks similar to

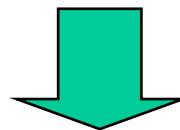
$$NS(f)$$



Some additional terms appear in the equations which account for ALL missing interactions between the resolved and the unresolved fields

## Scale separation. Cont'd

$$\begin{aligned}\nabla \cdot \mathbf{u} &= 0 \\ \frac{\partial \mathbf{u}}{\partial t} + \nabla \cdot (\mathbf{u} \otimes \mathbf{u}) &= -\nabla p + \nu \nabla^2 \mathbf{u}\end{aligned}$$



$$\begin{aligned}\mathbf{u} &= (u_1, u_2, u_3)^T \\ p &= P/\rho\end{aligned}$$

$$\begin{aligned}[a, b] f &= a \circ b(f) - b \circ a(f) \\ \mathcal{B}(\mathbf{u}, \mathbf{v}) &= \mathbf{u} \otimes \mathbf{v}\end{aligned}$$

$$\begin{aligned}\nabla \cdot \bar{\mathbf{u}} &= -A_1 \\ \frac{\partial}{\partial t} \bar{\mathbf{u}} + \nabla \cdot (\bar{\mathbf{u}} \otimes \bar{\mathbf{u}}) &= -\nabla \bar{p} + \nu \nabla^2 \bar{\mathbf{u}} - (A_2 + A_3 + A_4)\end{aligned}$$

with

$$\begin{aligned}A_1 &= [\mathcal{F}, \nabla \cdot] \mathbf{u} \\ A_2 &= \nabla \cdot [\mathcal{F}, \mathcal{B}] (\mathbf{u}, \mathbf{u}) \\ A_3 &= [\mathcal{F}, \nabla \cdot] \mathcal{B}(\mathbf{u}, \mathbf{u}) + [\mathcal{F}, \nabla] p + \nu [\mathcal{F}, \nabla^2] \mathbf{u} \\ A_4 &= \left[ \mathcal{F}, \frac{\partial}{\partial t} \right] \mathbf{u}\end{aligned}$$

- $A_1 \dots A_4$  additive functions of the original field and cannot be computed directly
- $A_1, A_3, A_4$  : possible commutation errors between operators  $\mathcal{F}$  and  $\partial_t, \partial_i$
- SSO chosen such that it commutes with differential operators ( $A_1 = A_3 = A_4 = 0$ ) ...

## Scale separation. Cont'd

$$f = \bar{f} + f'$$

**RANS formalism:**  $\bar{f} = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^{i=N} f_i$

$$\nabla \cdot \bar{\mathbf{u}} = 0$$
$$\frac{\partial}{\partial t} \bar{\mathbf{u}} + \nabla \cdot (\bar{\mathbf{u}} \otimes \bar{\mathbf{u}}) = -\nabla \bar{p} + \nu \nabla^2 \bar{\mathbf{u}} - \nabla \cdot \tau_{RANS}$$

**LES formalism:**  $\bar{f}(\mathbf{x}, t) = G \star f(\mathbf{x}, t)$   
 $= \int_0^{+\infty} \int_{\Omega} G(\bar{\Delta}(\mathbf{x}, t), \mathbf{x} - \xi, t - t').f(\xi, t').d\xi.dt'$

$$\nabla \cdot \bar{\mathbf{u}} = 0$$
$$\frac{\partial}{\partial t} \bar{\mathbf{u}} + \nabla \cdot (\bar{\mathbf{u}} \otimes \bar{\mathbf{u}}) = -\nabla \bar{p} + \nu \nabla^2 \bar{\mathbf{u}} - \nabla \cdot \tau_{SGS}$$

## Scale separation. Cont'd

- Reynolds tensor:

$$\tau_{TRANS} = \overline{\mathbf{u}' \otimes \mathbf{u}'}$$

→ A mathematical closure has to be introduced to represent the effect of the Reynolds stresses (first order closures, second-order analysis, ...)

- Subgrid Scale Tensor:

$$\tau_{SGS} = \overline{\mathbf{u}' \otimes \mathbf{u}'} - \overline{\mathbf{u}'} \otimes \overline{\mathbf{u}'}$$

→ Need for model for the interaction of the non resolved scales on the resolved scales

- Example:

$$\tau_{ij} - \frac{1}{3} \tau_{kk} \delta_{ij} = -2\nu_t \overline{S}_{ij}$$

# Scale separation. Cont'd

- LES : production zones must be resolved

## **NB for LES:**

$$\text{In general, } \bar{\bar{f}} = G \star G \star f \neq \bar{f} \quad \bar{f}' = G \star (Id - G) \star f \neq 0$$

Most LES are performed in physical space (numerical schemes → additional dissipation)



The scheme acts as a numerical filter which damps the highest resolved frequencies



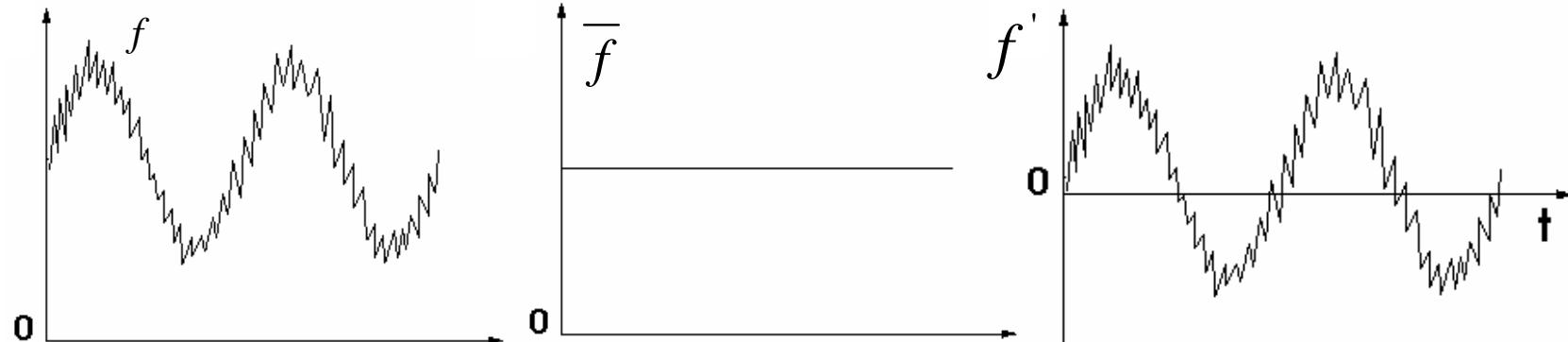
It is generally impossible to get access to the effective filter of the simulation



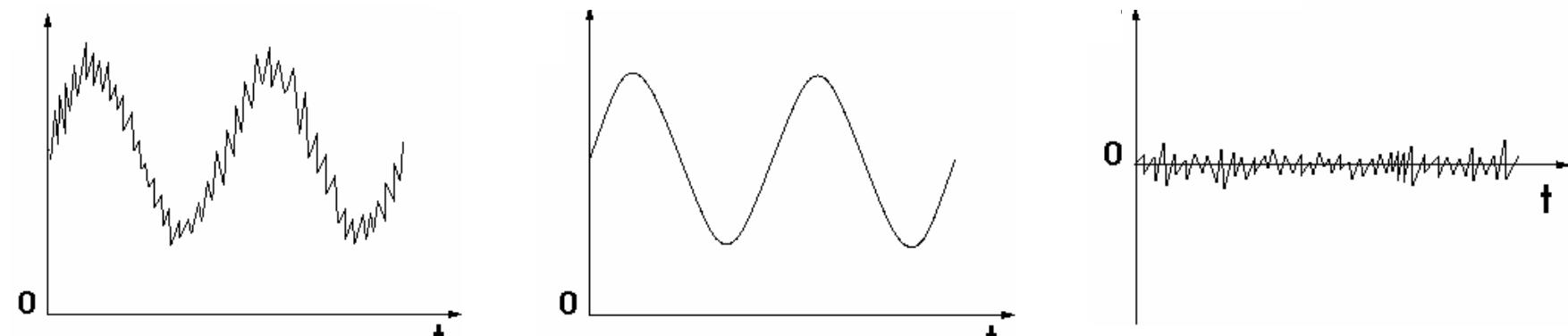
ILES, MILES ...

# Unsteady statistical approach (URANS)

*Reminder RANS:*  $\langle f \rangle_T = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T f(s) ds$

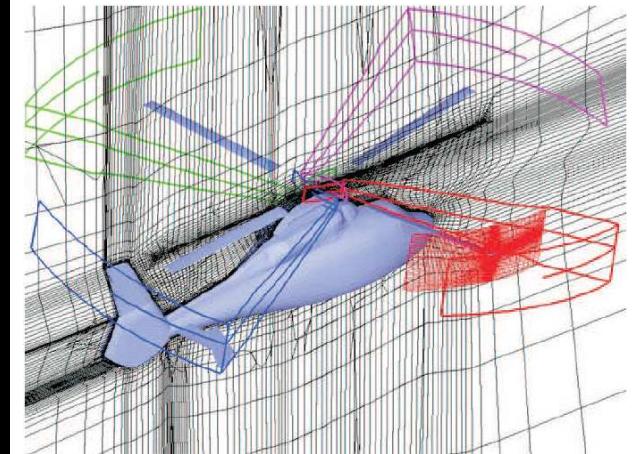
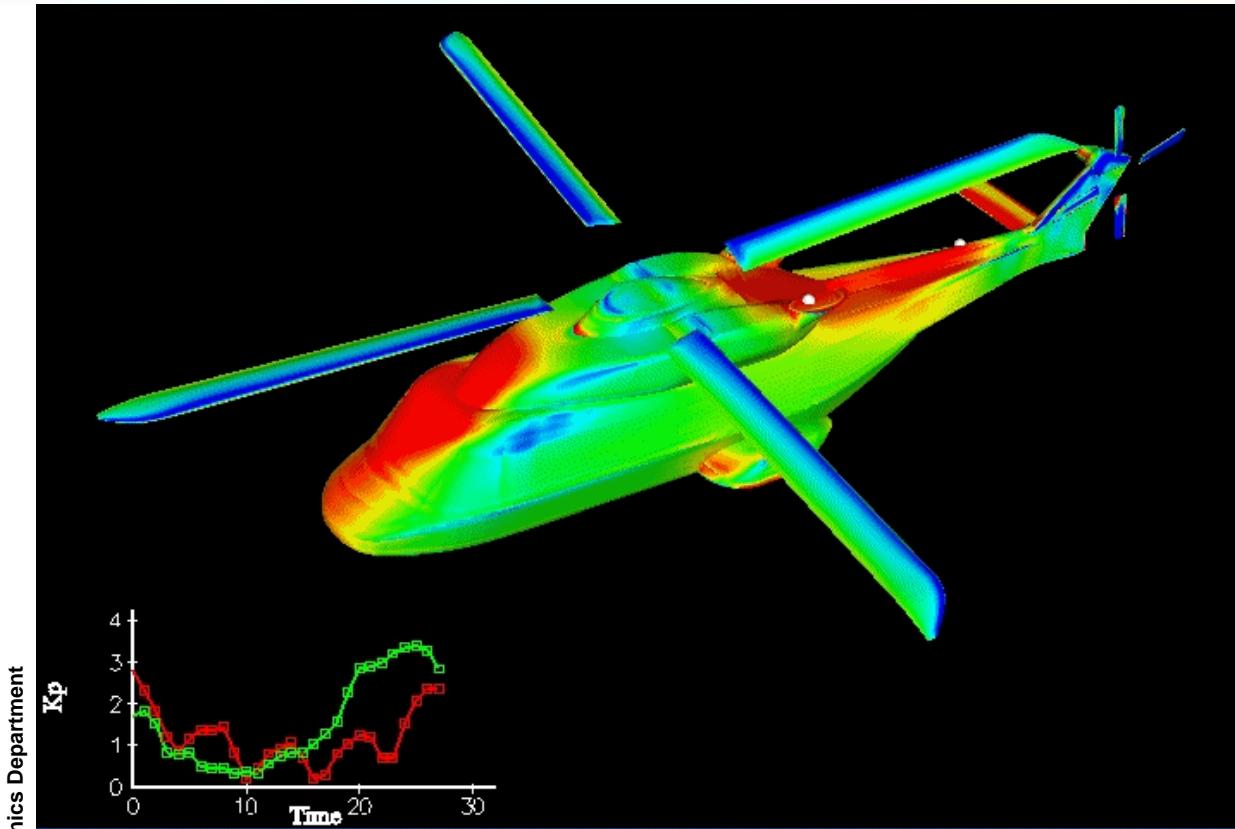


*Proposal URANS:*  $\bar{f}(t) = \frac{1}{T} \int_{t-T}^t f(s) ds \quad \text{with} \quad T \gg \tau$



→ Scale separation (i.e. spectral gap) between unsteadiness of the Mean field (time scale  $\theta$ ) / turbulence (time scale  $\tau$ )

# Unsteady statistical approach (URANS)



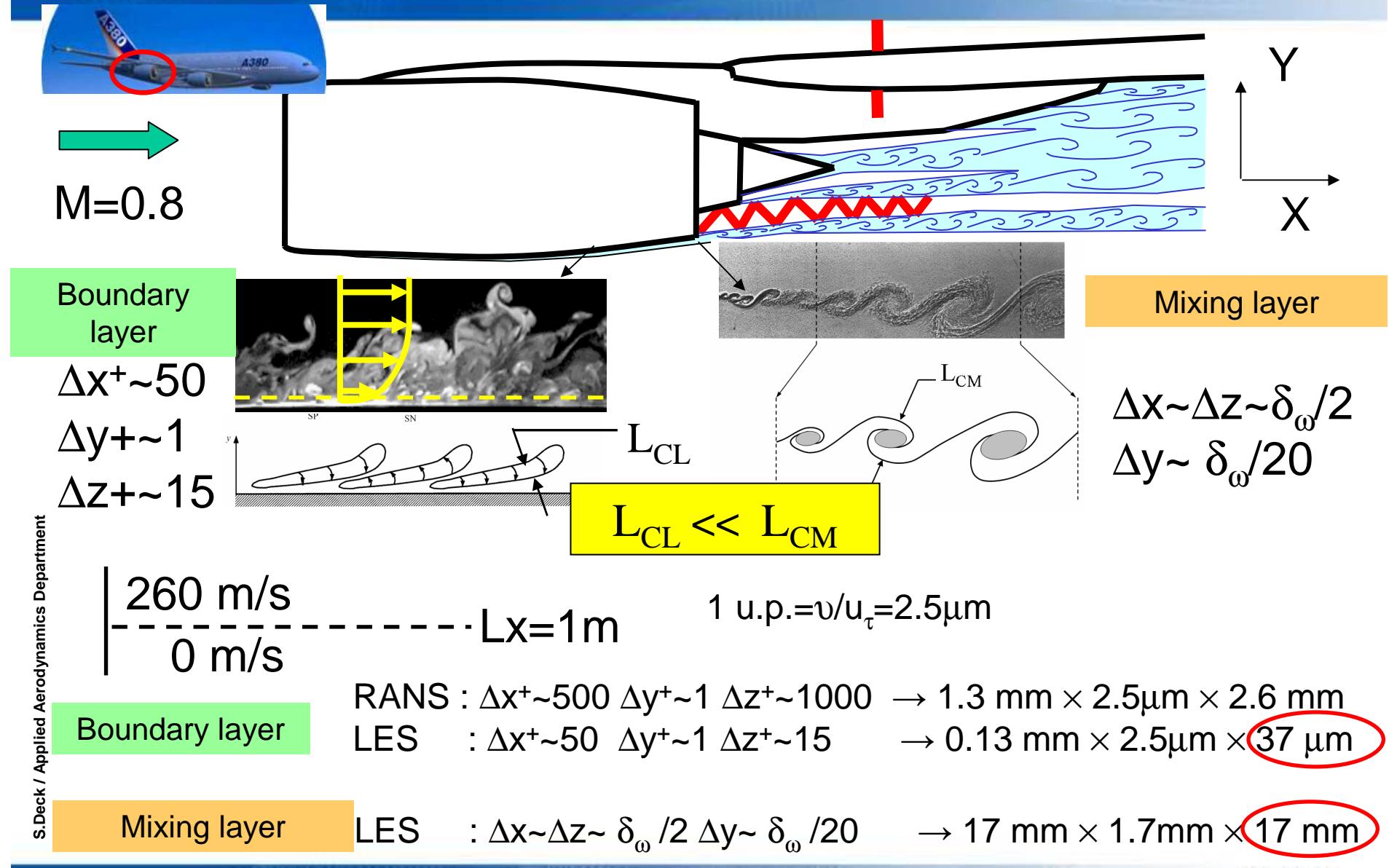
(T. Renaud, ONERA)

- URANS: turbulence model unchanged (here  $k-\omega$  model)
- Chimera method (difficulty of the grid design)
- ALE method
- Boundary conditions

# Contents

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# Turbulence modelling : the large scales. Production mechanisms.

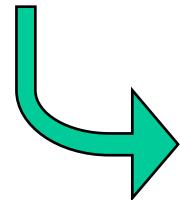


# Motivations of hybrid RANS/LES

Motivation : combine the best features of RANS and LES

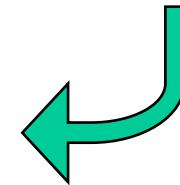
## RANS

- attached flow
- low computational cost



## LES

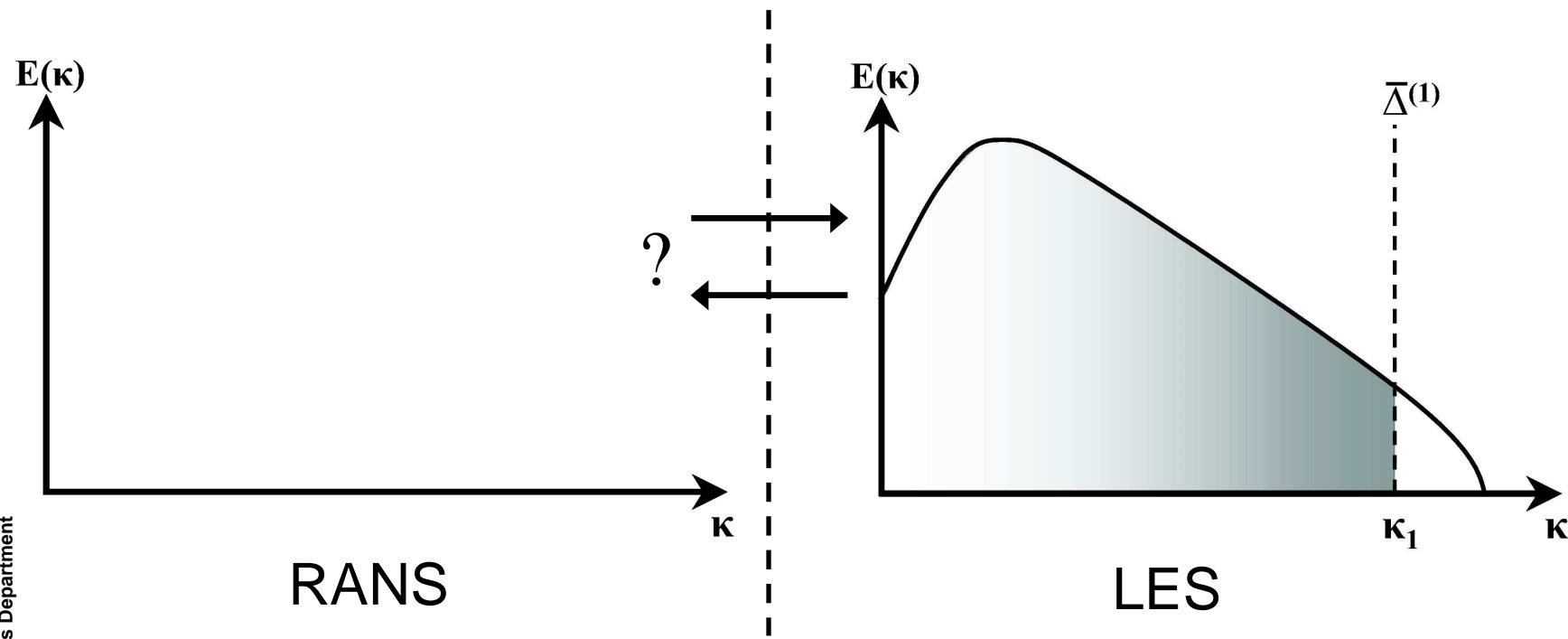
- separated flow
- high computational cost



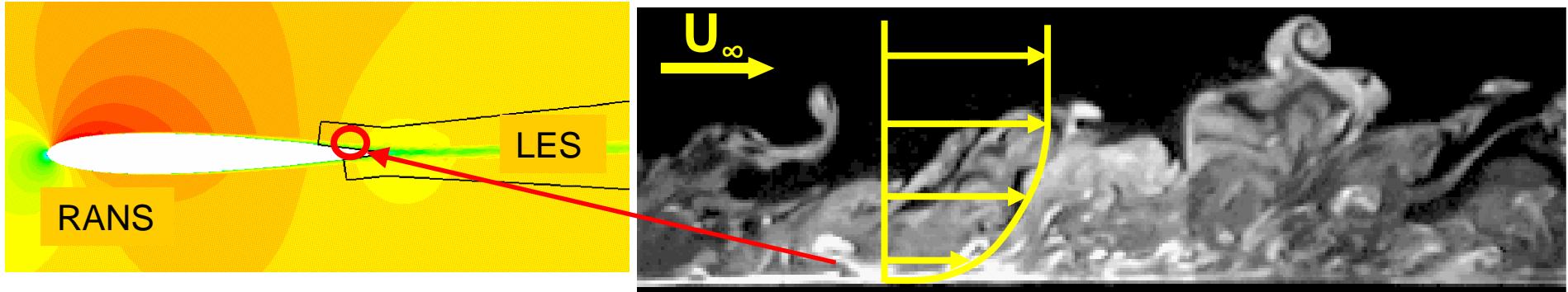
## Hybrid RANS/LES

# Rappels sur les opérateurs de séparation d'échelles (5/5)

resolved turbulent kinetic spectra

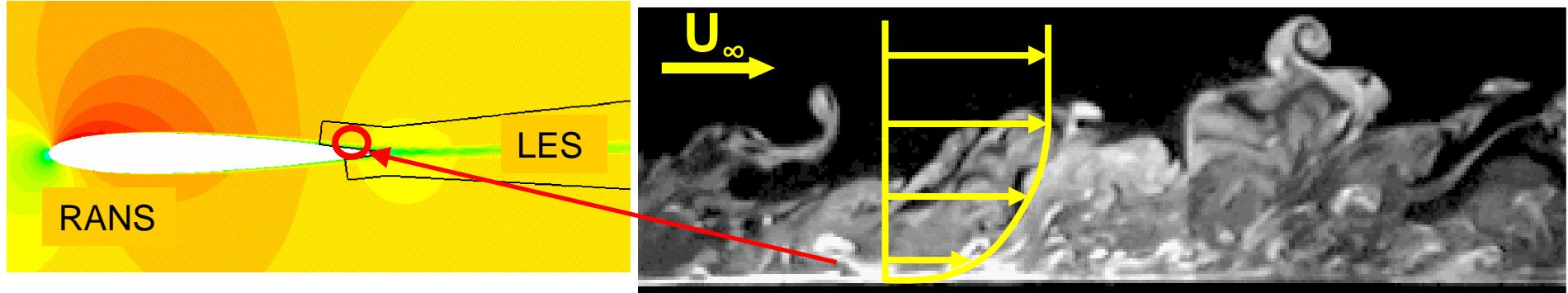


# DISCUSSION. Wall turbulence simulation at High Reynolds number



- Natural use of “DES-type” methods: TBL treated in RANS mode  
→ inappropriate in flows situations sensitized to the history of the upstream turbulence (flow of category III)
- RANS provides a solution that varies with a time-scale  $\gg \Delta t$
- LES solves small 3D structures  
→ the inlet TBL has to account for these small eddies

# DISCUSSION. Wall turbulence simulation at High Reynolds number

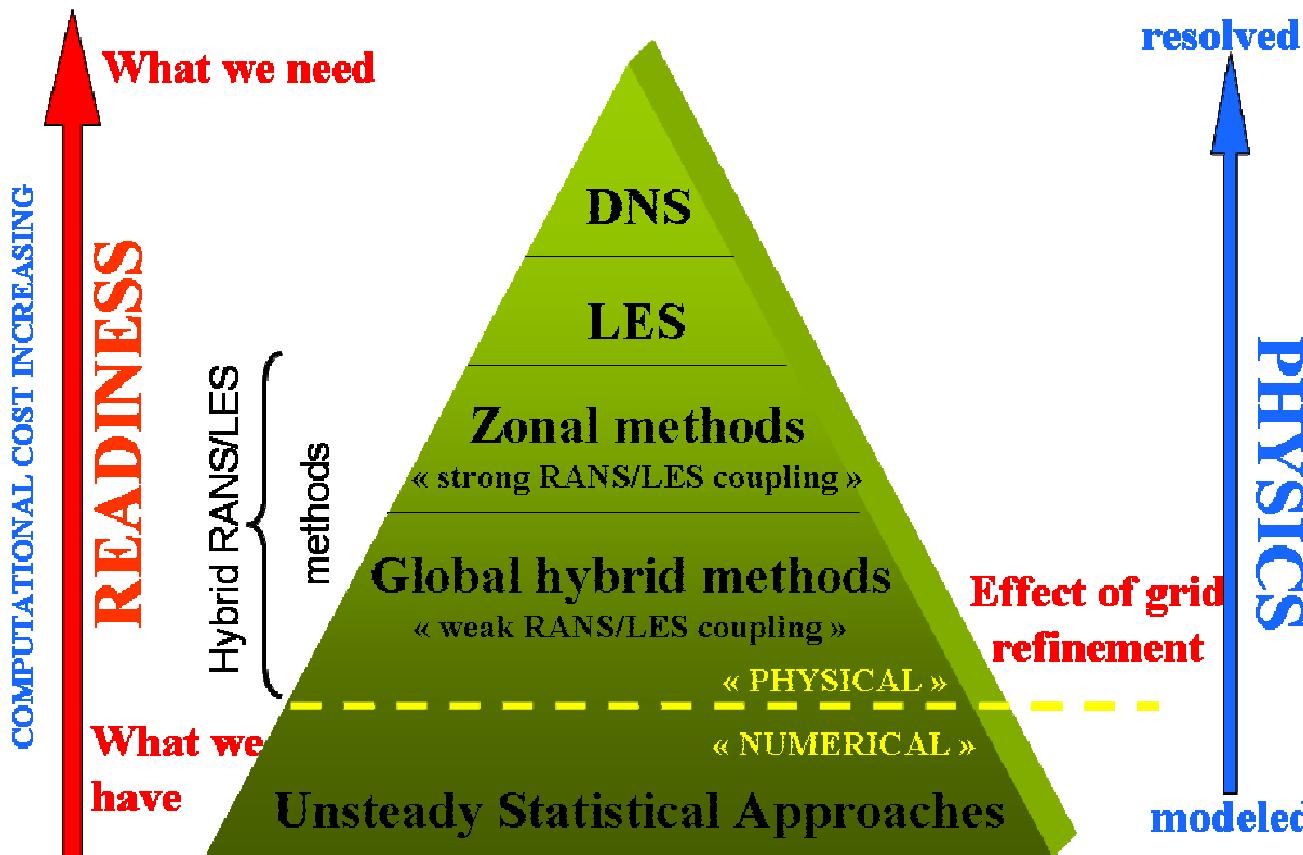


## DIFFICULTIES:

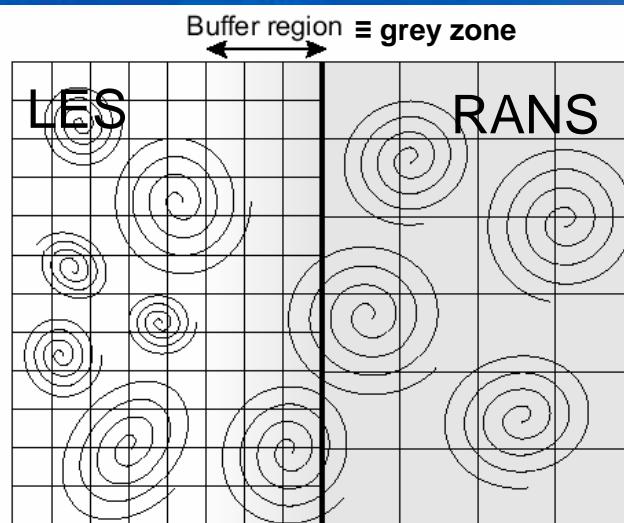
- Regenerate wall turbulence from only a statistical description !
- Prescription of a flowfield of the same nature as the one expected by the simulation  
One has to specify an unsteady vortical flowfield that satisfies if possible :
  - energy spectra
  - 1<sup>st</sup> and 2<sup>nd</sup> order statistics
  - Phase correlation between the different modes: the most « tricky » since it describes the shape of the eddies, *i.e.* the intricate nature of turbulence

# Classification of unsteady approaches

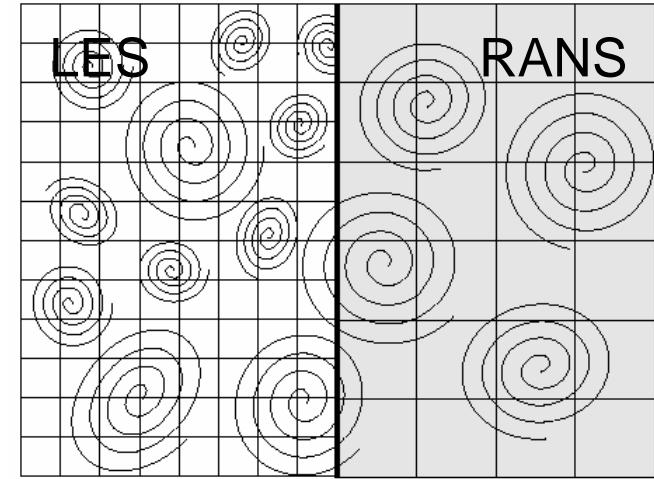
Modeling level  $\equiv$  Compromise solution (physics / CPU cost)



# Global and Zonal RANS/LES approaches



Global methods (*Flow problems of cat I*)



Zonal methods (*Flow problems of cat II*)

## CLASSIFICATION I: treatment of the RANS/LES interface

- global methods: continuous treatment of the flow variables at the interface  
→ LES content generated progressively through a grey zone
- *zonal methods*: discontinuous treatment of the RANS/LES interface  
→ definition of interface variables to construct a transfer operator at the interface

## CLASSIFICATION II: problem of interest

- Cat I: massively separated flows (strong instabilities overwhelming inherited TBL turbulence)
- Cat II: flows sensitized to the history of the upstream turbulence

## Global and Zonal approaches (2) global hybrids : smooth transition

- Key idea: switch in eddy/subgrid viscosity
  - • Direct change in subgrid viscosity scaling
  - • Change in transport equations for turbulent quantities
- Common implementation
  - • Same number of variables
  - • 0-2 equations
  - • Massively separated flows ( $\rightarrow$  reduced buffer zone)

# Examples of applications

## Eddy viscosity scaling

$$\tau = \alpha \tau^{\text{RANS}}$$



$$\nu_t = \alpha \nu_t^{\text{RANS}}, \quad 0 \leq \alpha \leq 1$$

*Linear models*

Speziale (1997)

(*Very Large Eddy Simulation, VLES*)

$$\alpha = \left[ 1 - \exp \left( -\frac{\beta \Delta}{L_K} \right) \right]^n$$

Batten et al. (2000)

(*Limited Numerical Scales, LNS*)

$$\alpha = \frac{\min [(\text{LV})_{\text{LES}}, (\text{LV})_{\text{RANS}}]}{(\text{LV})_{\text{RANS}}}$$



$$\alpha = \min \left\{ \frac{\nu_t^{\text{LES}}}{\nu_t^{\text{RANS}} + \eta}, 1 \right\}$$

Easy to implement...

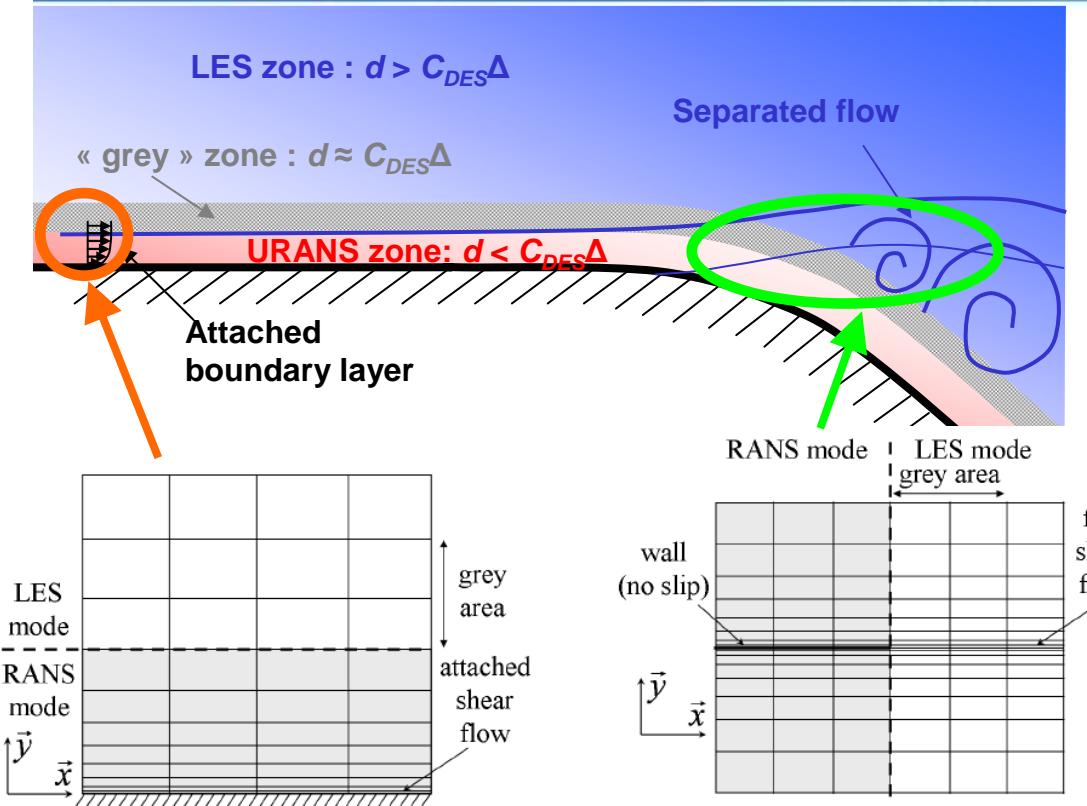
# Detached Eddy Simulation – Modelled Stress Depletion – Grid Induced Separation

→ DES97 (Spalart et al. , 1997)

$$\tilde{v} \sim S\tilde{d}^2 \quad \tilde{d} = \max(d, C_{DES}\Delta) \quad \Delta = \max(\Delta_x, \Delta_y, \Delta_z)$$

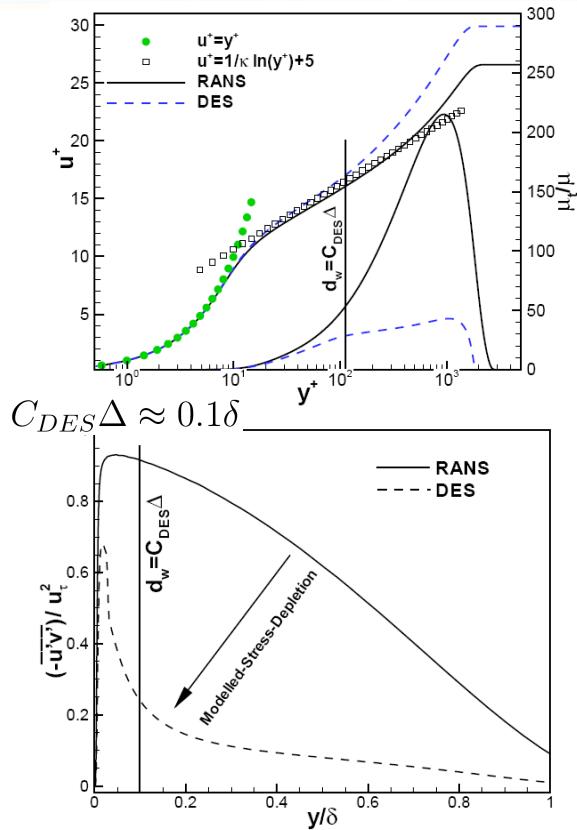
- natural use in thin boundary layers and in massive separation
  - The needs of different flow regions places conflicting demands on the grid
    - $\Delta_{\text{tangential}} > \delta$  requirement may be easily violated in industrial applications
    - isotropic LES cells + structured grid refinement in regions not intended to be handled by LES
- (NB: practically unavoidable in regions of high geometric curvature and/or thick BLs)

# Detached Eddy Simulation – Modelled Stress Depletion – Grid Induced Separation



(a) "transversely induced MSD"

(b) "longitudinally induced MSD"



- Weakened  $v_t$  → Modelled Stress Depletion → skin friction  $\downarrow$  → premature separation
- Delay in the formation of instabilities in free shear layers
- Damping of the growth of instabilities through advection of RANS viscosity

## 4. Solutions against GIS: ZDES – DDES - SDES

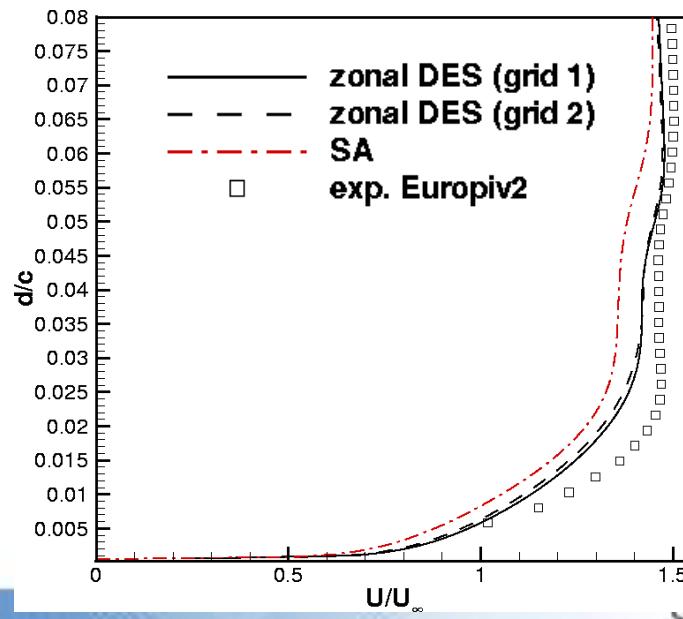
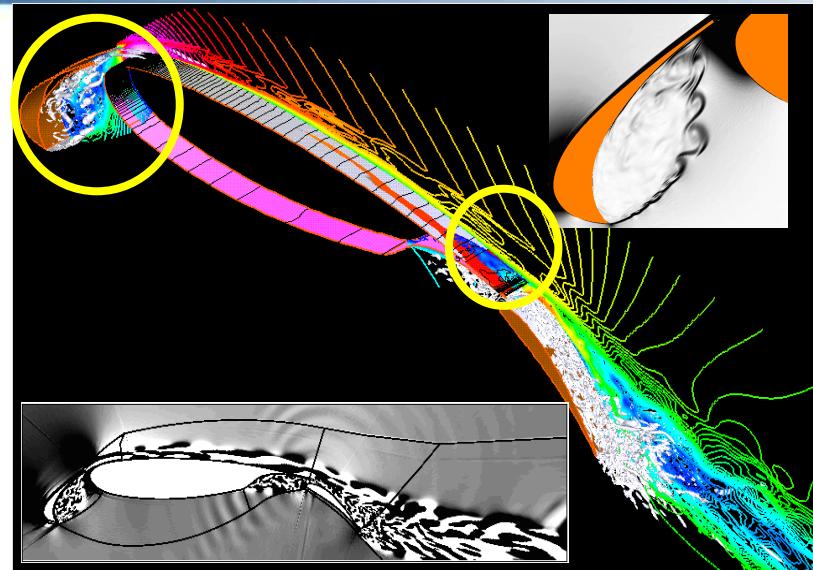
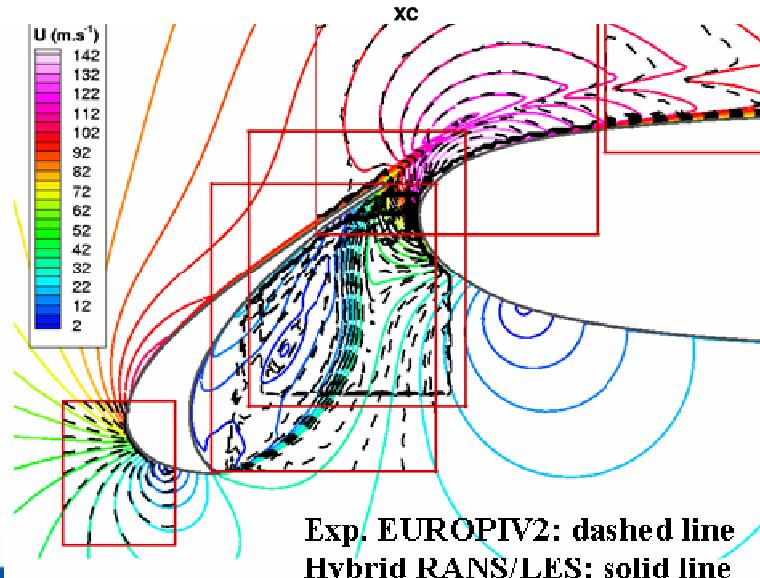
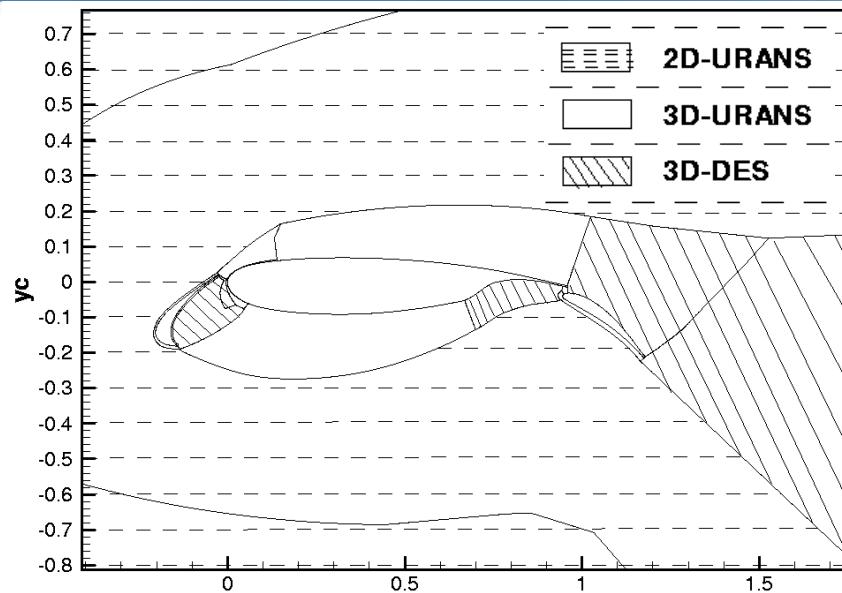
### → ZDES (Deck, AIAA J., vol 43, No 11, 2005)

- the user selects individual RANS and LES domains (analogous to RANS/LES coupling)
- grid refinement focused on regions of interest without corrupting the BL properties
- Near-wall functions disabled,  $\Delta = (\Delta x \Delta y \Delta z)^{1/3}$  or  $\Delta = \Delta_\omega$
- switches very quickly to LES mode
- Well adapted when detachment occurs near sharp edges

### → DDES (Spalart et al. , TCFD, vol 20, 2006)

- modification of the length scale  $\tilde{d} = d_w - f_d \max(0., d_w - C_{DES}\Delta)$   $f_d = 0 \rightarrow$  RANS
- the model “refuses” LES mode, if it believes it is in a boundary layer
- well adapted when separation location is not known *a priori*

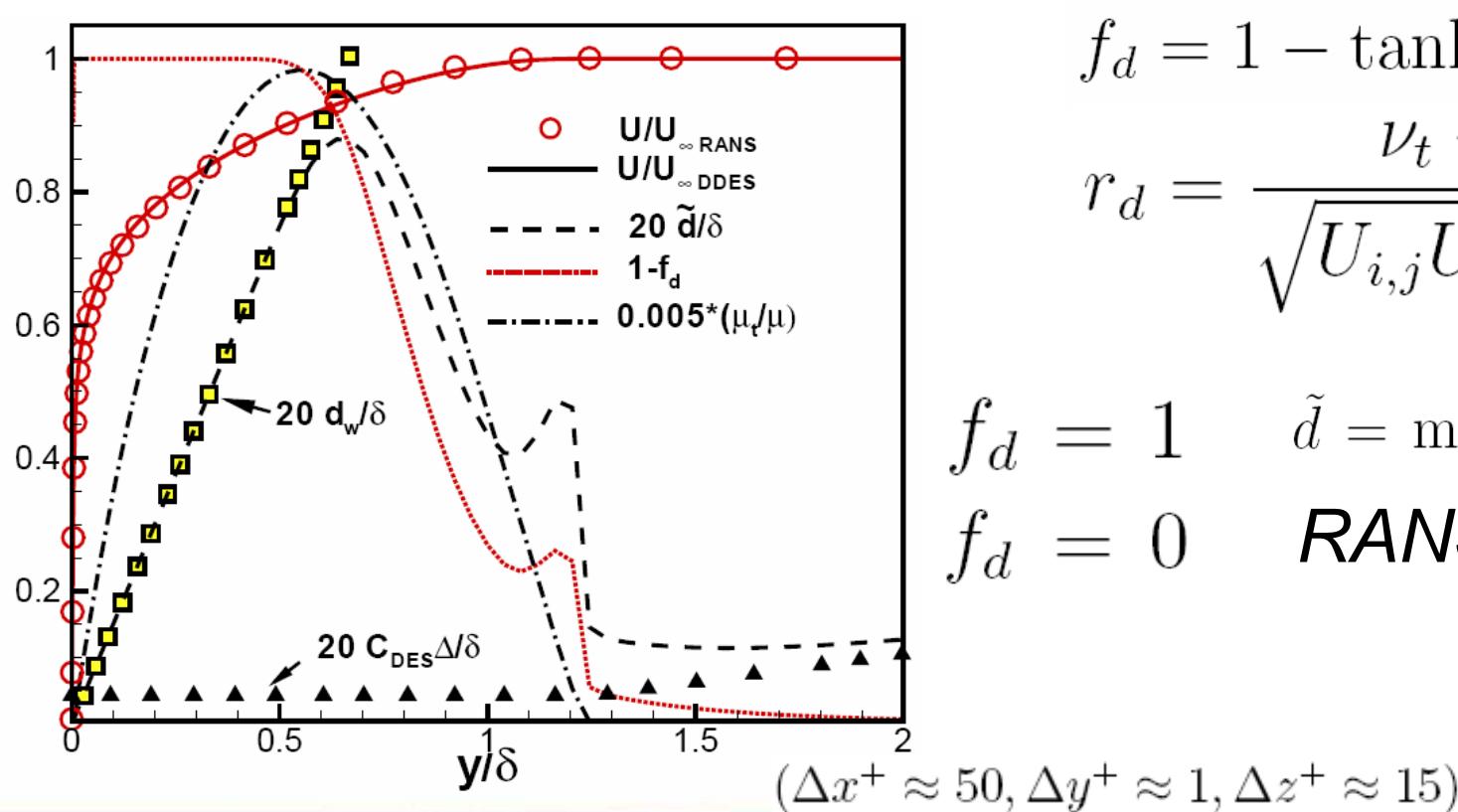
# Zonal Detached Eddy Simulation (ZDES)



# Delayed Detached Eddy Simulation (DDES)

- approche « automatique » capable de refuser le passage en mode LES
- collaboration Boeing / Univ. of Arizona / NTS / ONERA

$$\tilde{d} = d_w - f_d \max(0., d_w - C_{DES}\Delta)$$



$$f_d = 1 - \tanh([8r_d]^3)$$

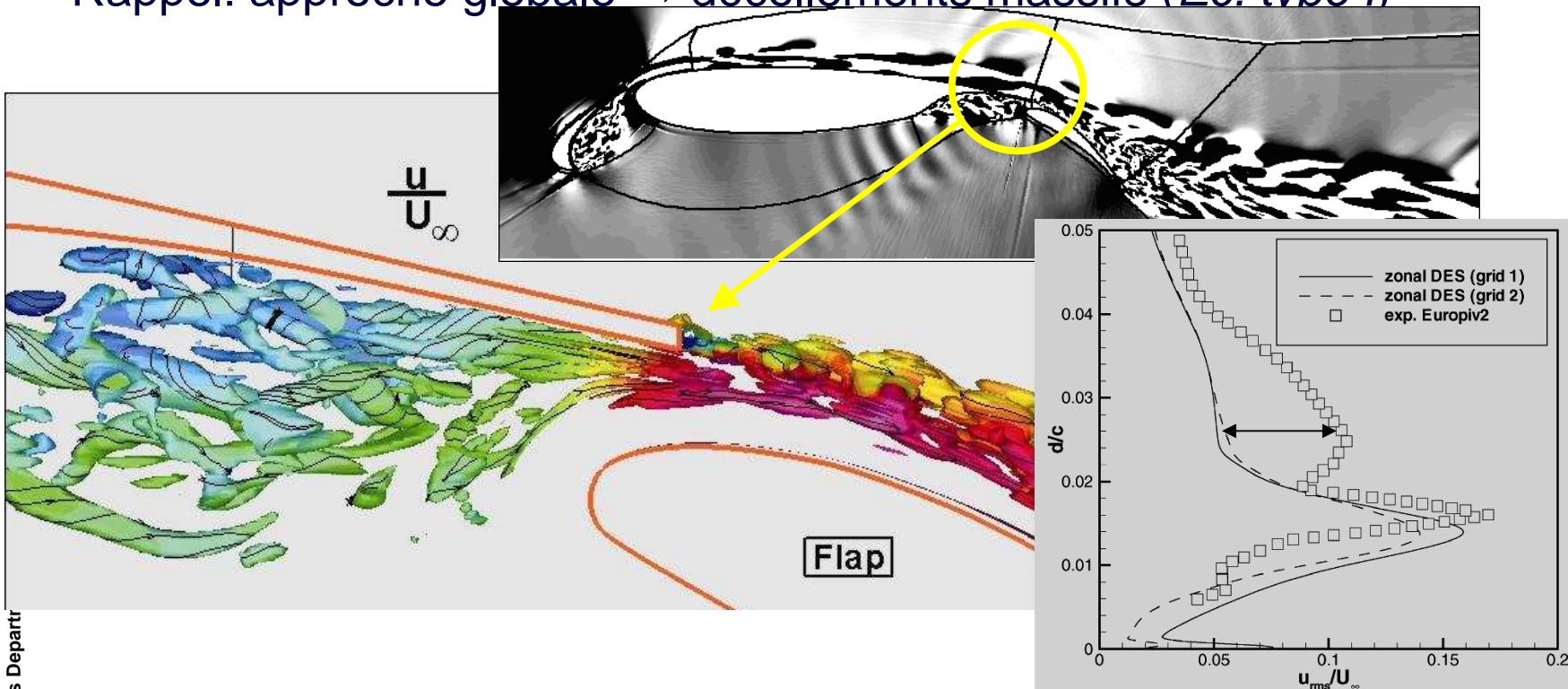
$$r_d = \frac{\nu_t + \nu}{\sqrt{U_{i,j}U_{i,j}}\kappa^2 d_w^2}$$

$$f_d = 1 \quad \tilde{d} = \min(d_w, C_{DES}\Delta)$$

$$f_d = 0 \quad RANS$$

# Stimulated Detached Eddy Simulation (SDES)

- Rappel: approche globale → décollements massifs (*Ec. type I*)



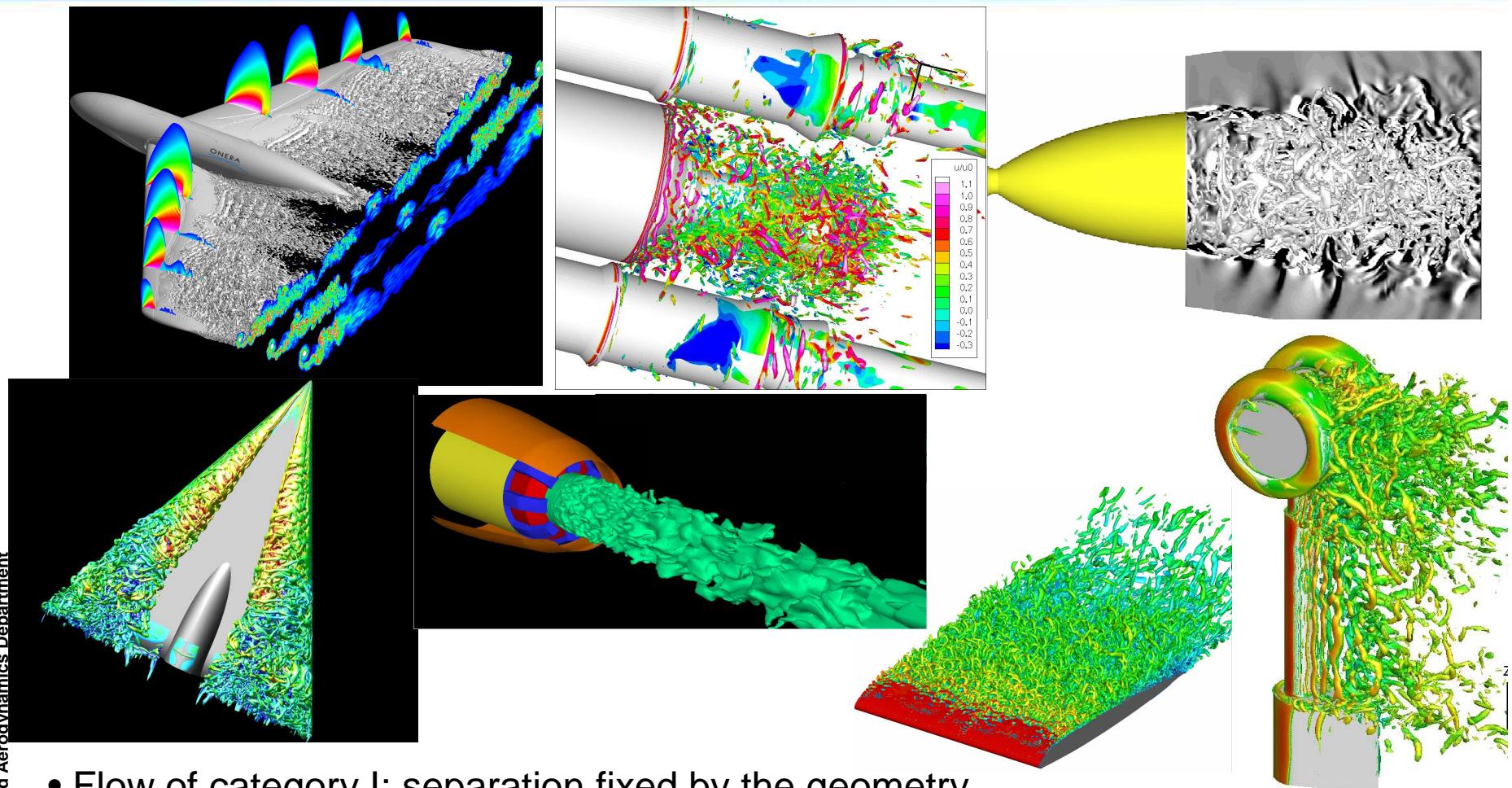
Développement de conditions aux limites instationnaires en RANS/LES

Turbulence pariétale → Utilisation « non-naturelle » des techniques de type DES

Stimulated Detached Eddy Simulation (2006-2007 ...)

- Traitement de  $\tilde{v}$  : remise à l'échelle et turbulence synthétique

# Applications

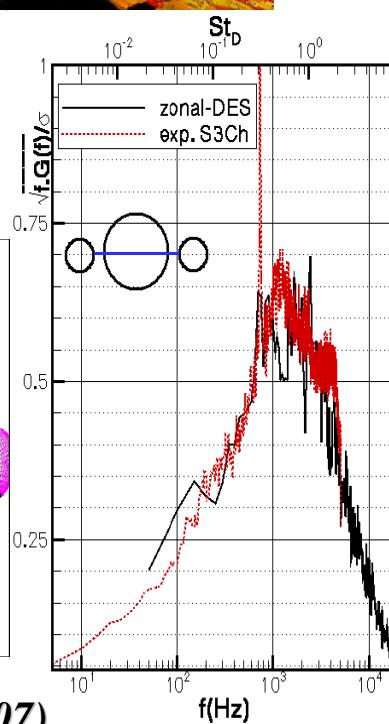
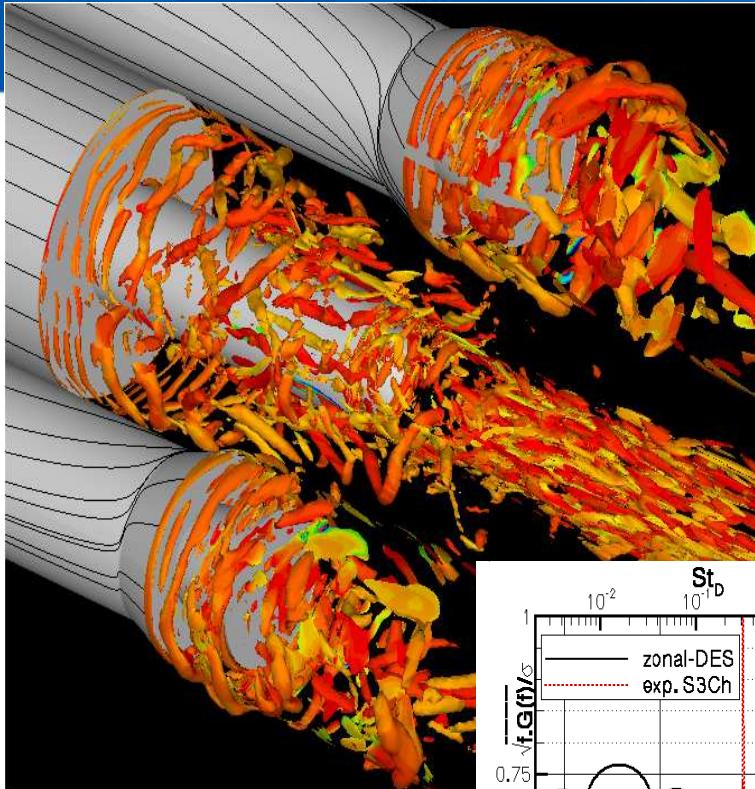


- Flow of category I: separation fixed by the geometry
- Flow of category II: separation fixed by a pressure gradient
- Flow of category III: include dynamics of the TBL

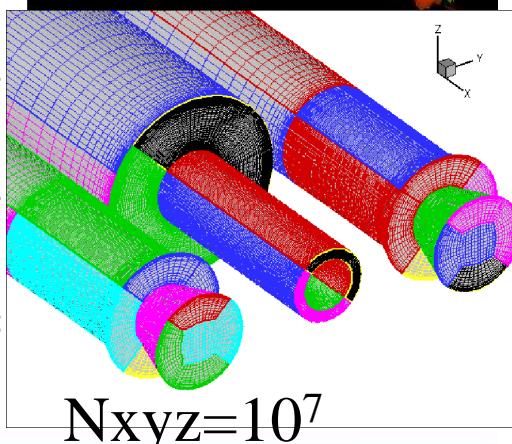
# Exploitation/Validation des calculs instationnaires

	<b>Niveau de validation</b>
1	<b>Efforts stationnaires</b> (portance, traînée, moment)
2	<b>Champ aérodynamique moyen</b> (profils de vitesse et de pression)
3	<b>Moments statistiques d'ordre 2</b> (rms, tensions croisées)
4	<b>Analyse spectrale en 1 point</b> (DSP)
5	<b>Analyse spectrale en 2 points</b> (spectres de cohérence et de phase)
6	<b>Ordre supérieur, temps-fréquence</b> (bi-cohérence, T. Ondelettes)

# ZDES of launcher afterbody flows

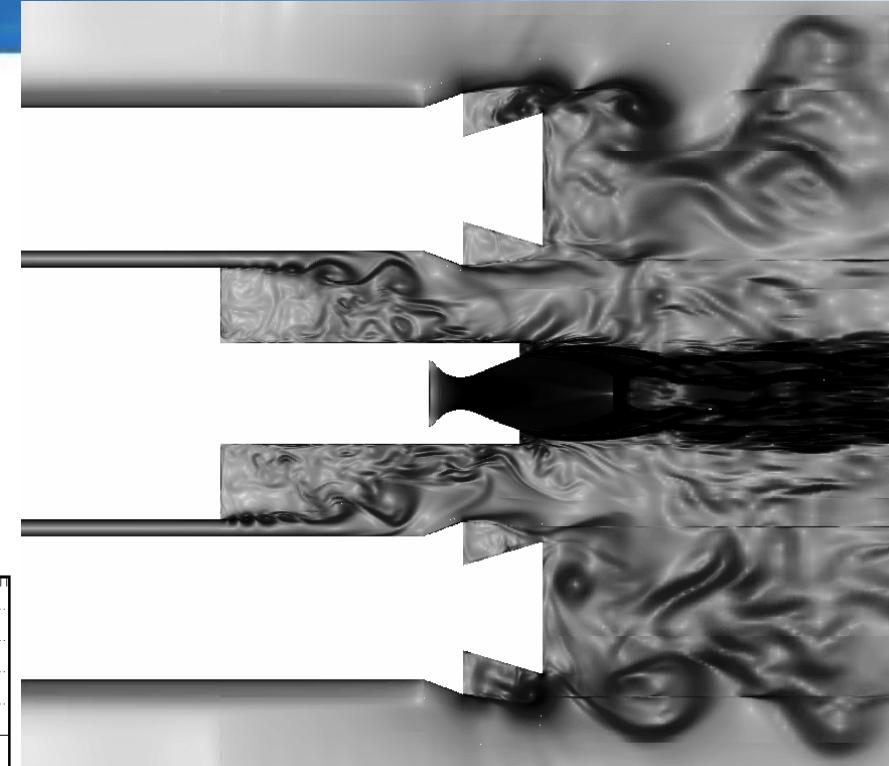


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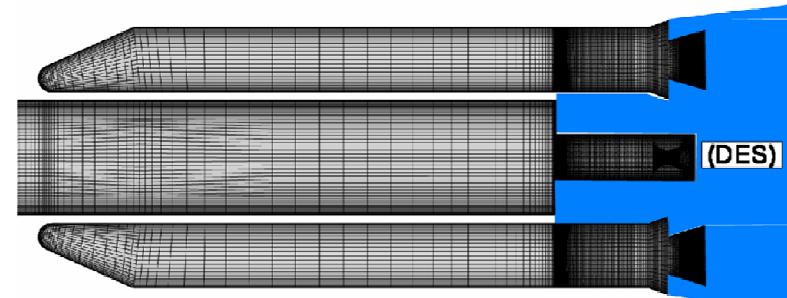


(Deck, Thépot, Thorigny 2007)

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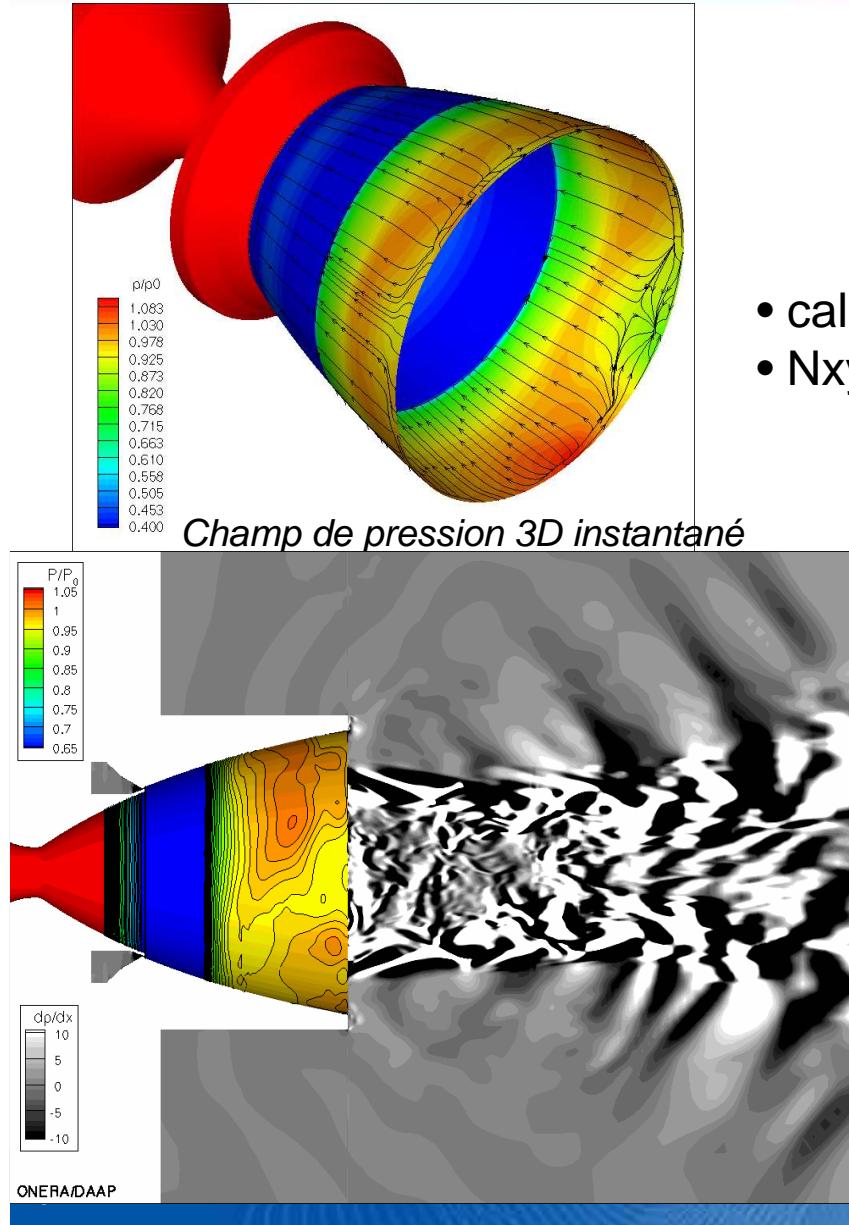


URANS

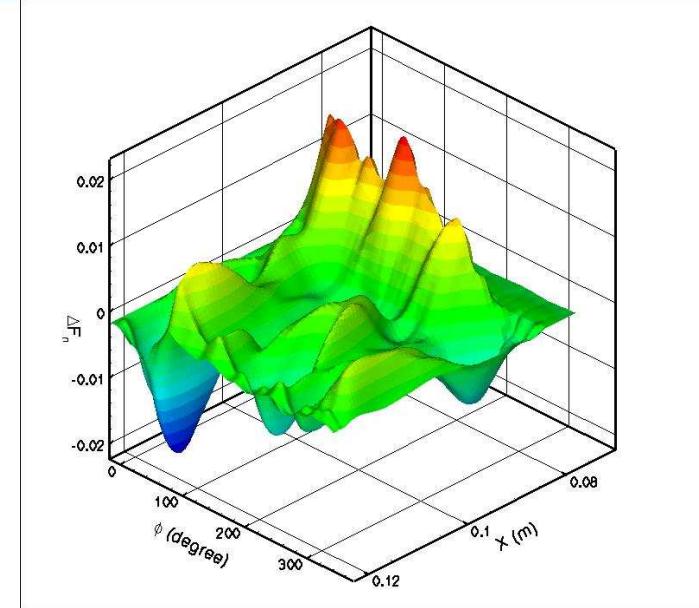


URANS

# Tuyères type V2 : charges latérales



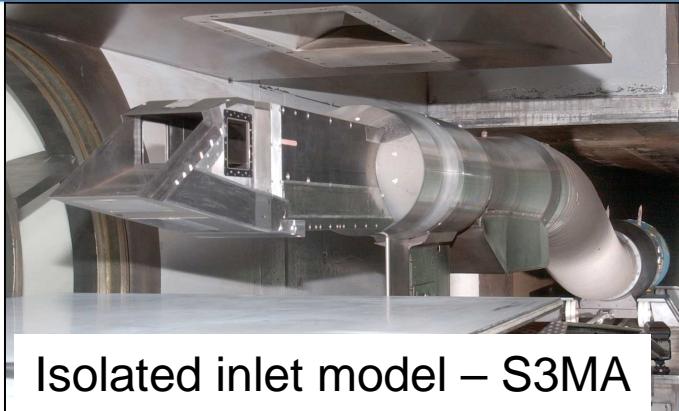
- calcul DDES
- $N_{xyz}=11.10^6$



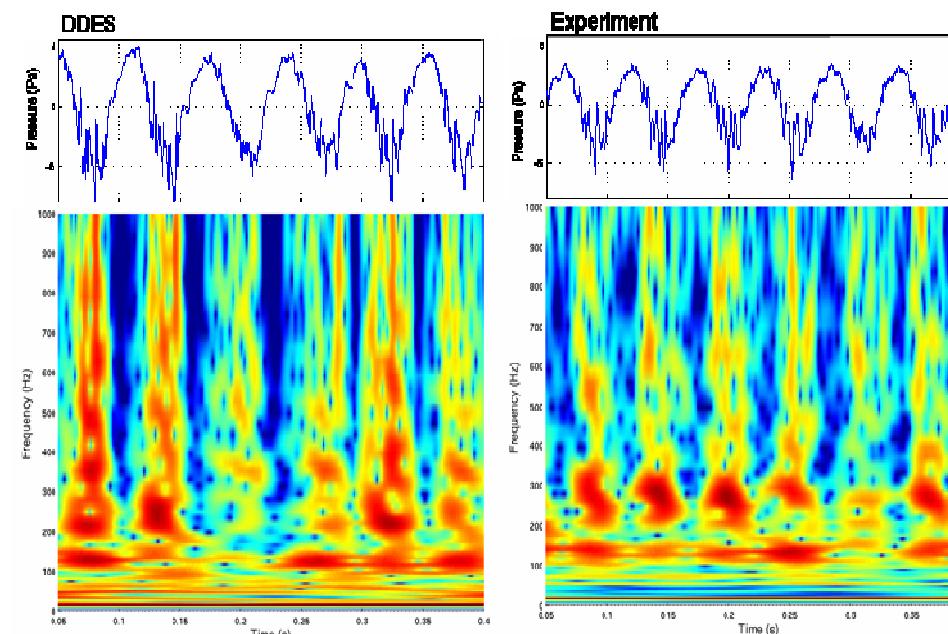
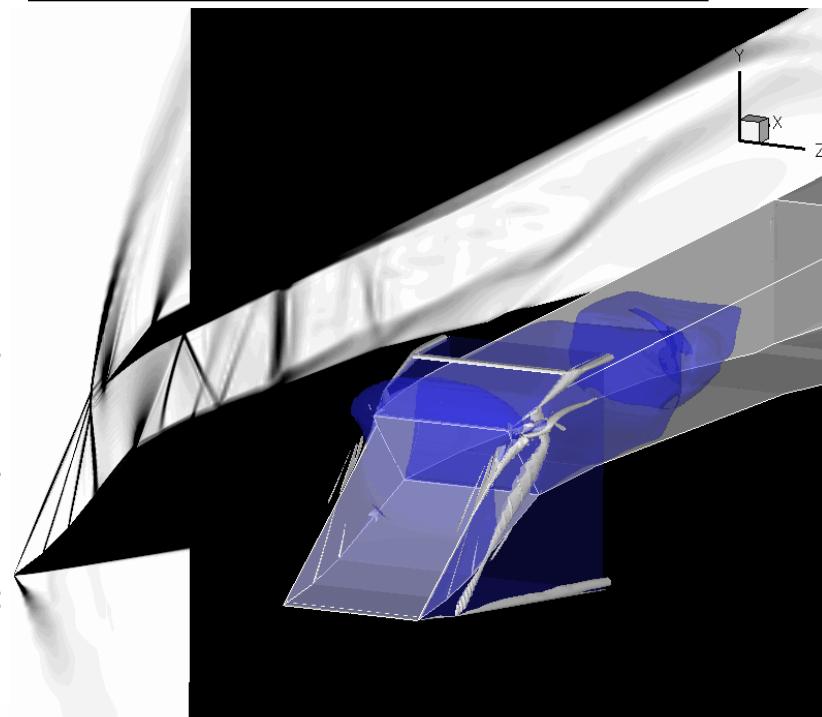
*Distribution spatiale de l'effort instantané*

- CFD: effort aérodynamique pur (i.e pas de correction d'inertie)
- accès à l'ensemble du champ aérodynamique
- Asymétrie du recollement de lèvre
- Possible origine des Side-Loads
-

# DDES of supersonic buzz in a rectangular mixed compression inlet



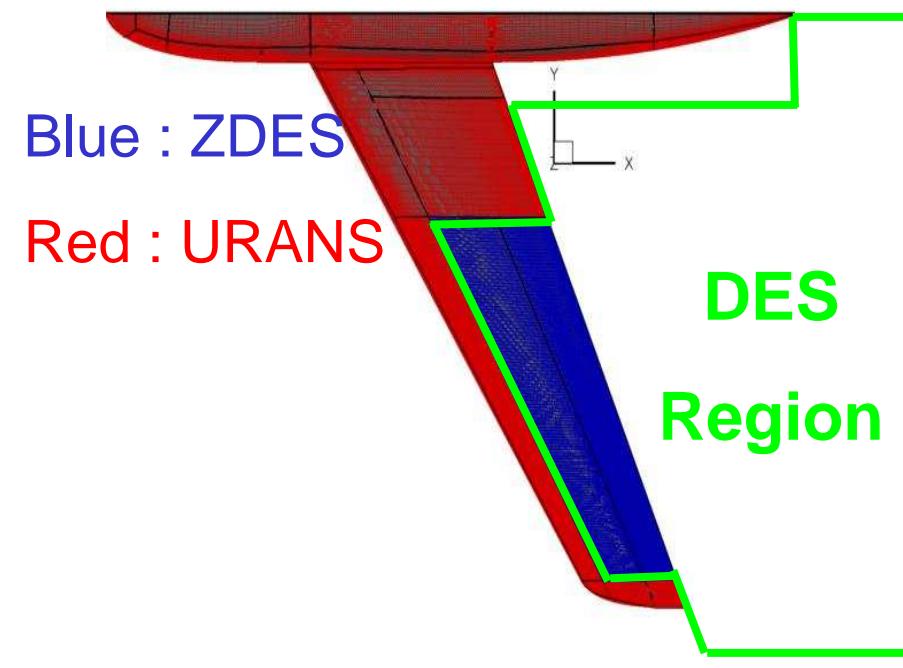
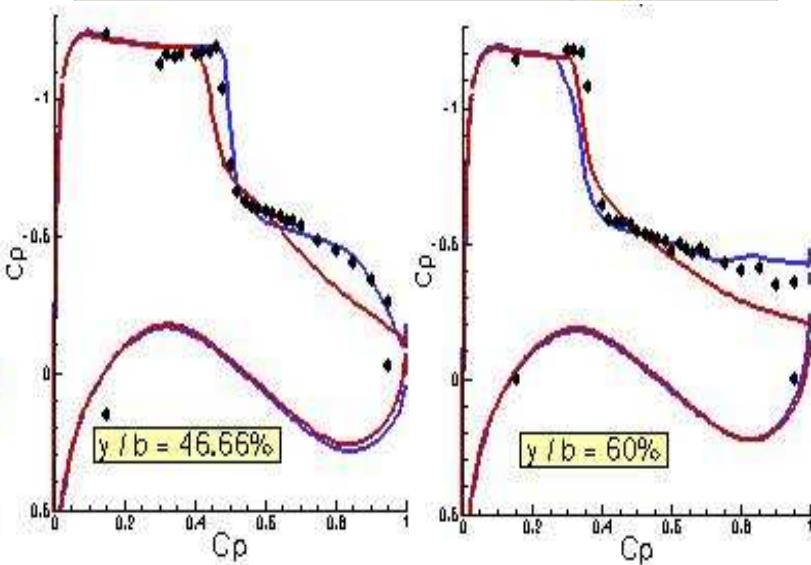
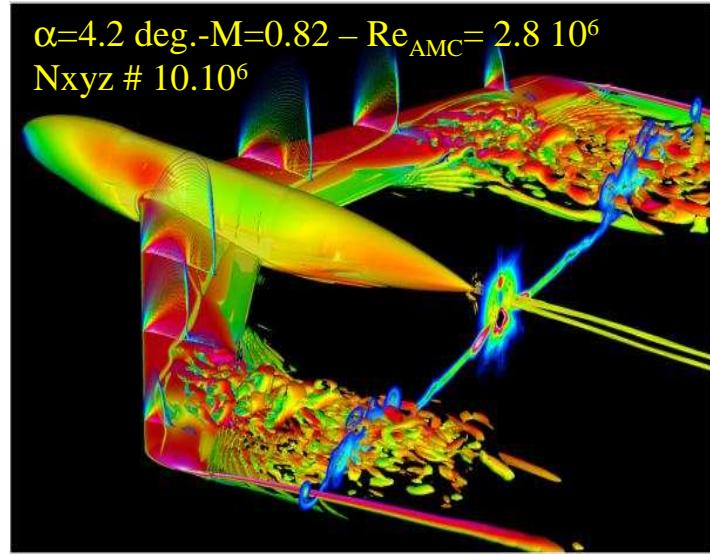
- high amplitude variation of the inlet mass flow and pressure
- can lead to thrust loss, engine surge, structural damage
- $N_{xyz}=20.10^6$ .  $Re=29.10^6$ .  $M=1.8$  (ONERA S3MA)



Wavelet transform

(Trapier et al., AIAA J., vol 46, No 1, 2008)

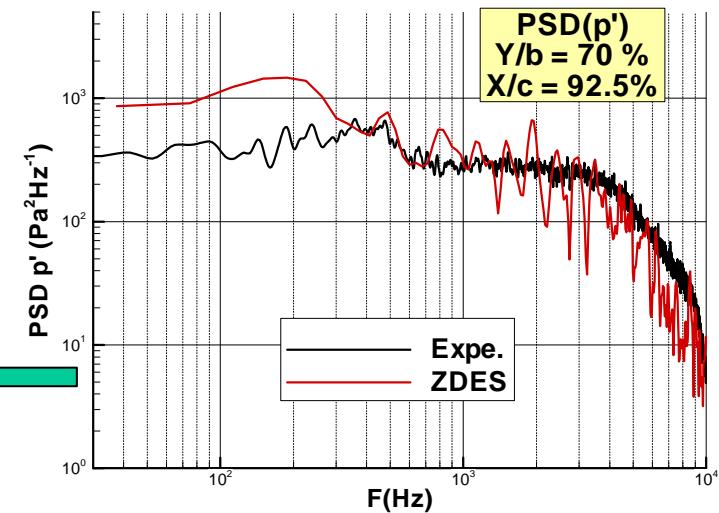
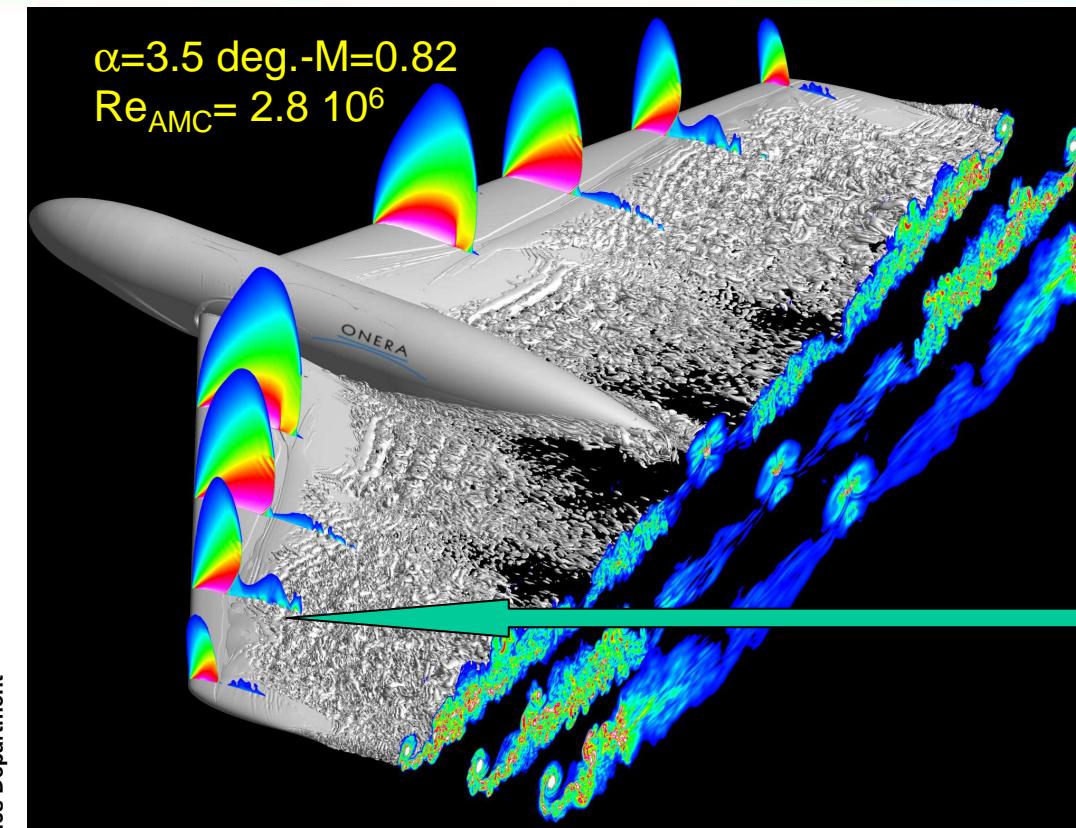
# ZDES of transonic buffet



- Wing body configuration (ONERA S2MA)
- $N_{xyz}=10.10^6$ . 84 blocks
- difficult case for hybrid RANS/LES
- intense separation / curved separation line
- steady solution with URANS
- separation underestimated by URANS
- mean shape of separated area well reproduced by ZDES

(Brunet, Deck, Corfou Symposium, Springer 2007)

# ZDES of transonic buffet (flow of category II)

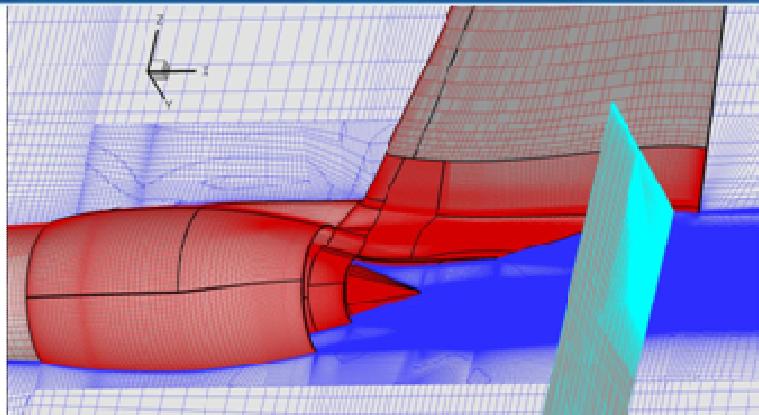


**elsA software**

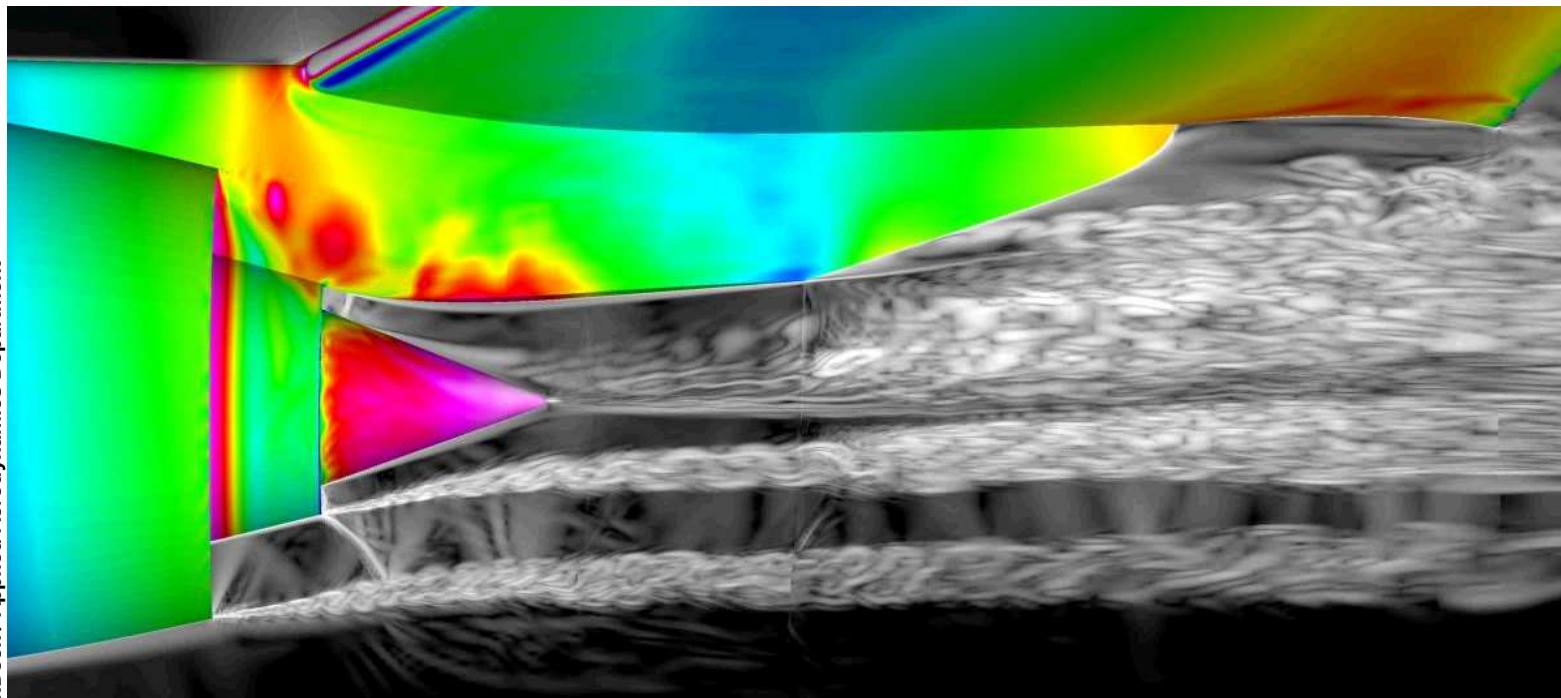
- Wing body configuration (ONERA S3Ch)
- $N_{xyz}=190.10^6$  (patch grid technique)
- 1024 cores
- WT walls / wing deformation measured during test taken into account
- difficult case for hybrid RANS/LES
- both  $d^I_{DES}$  &  $d^{II}_{DES}$  are used in the same calculation
- buffet dynamics well simulated

(V.Brunet, DAAP)

# ZDES of a civil aircraft jet engine configuration



- prévision des mécanismes de mélange, thermique et acoustique
- approche ZDES (AIAA J., vol 43, No. 11, 2005)
- $N_{xyz}=40.10^6$  pts – 73 blocs
- géométrie 3D / schémas numérique
- code industriel : **eIsA**

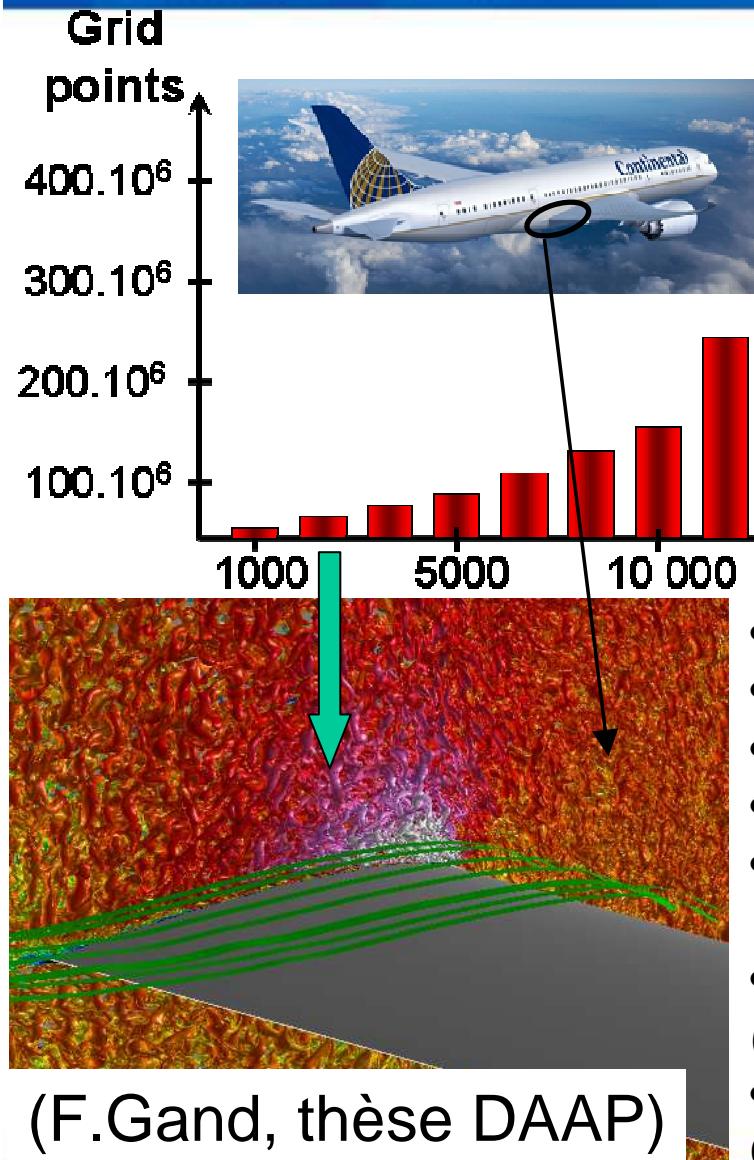


S.Deck / Applied Aerodynamics Department

V. Brunet and S. Deck. 3<sup>rd</sup> Symposium on hybrid RANS/LES, Gdansk, 2009)

(V.Brunet, DAAP)

## DISCUSSION. Simulation de la turbulence pariétale à grand Re Application aux écoulements de coins.



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- traînée parasite, tremblement
  - approche RANS mise en défaut
  - besoin d'une meilleure fiabilité des simulations des écoulements de coins (design jonction voilure/fuselage)
- LES d'une jonction aile fuselage simplifiée
  - $Re_\theta=2100$ .  $Re_c=3.10^5$   $M=0.15$ .
  - $Nxyz=65.10^6$ .  $\Delta t=0.5\mu s$
  - 8 processeurs NEC-SX8. 20000h CPU  $\rightarrow$  80ms
  - bonne comparaison avec les données exp.
- méthode de turbulence synthétique (SEM)  
(Pamiès et al. Phys. of Fluids, 21, 2009, thèse DAAP)
  - étendu actuellement à la ZDES pour réduire le coût CPU

# Conclusion

- Développement des méthodes RANS/LES incontournable et pour longtemps !
- Coût important de validation
  - Nécessité de validation de niveau > 3
  - Promotion d'expériences « calculables » (validation, fiabilité des calculs)
- Retour sur 2045 ...
  - Si l'efficacité énergétique des ordinateurs (J/flop ou kW.h/Giga.flop) approche un minimum, le coût nécessaire pour résoudre la CL turbulente à grand Reynolds sera inaccessible!
  - 2009: coût énergétique annuel (électricité)~5% du coût d'achat
  - Sera t'il rentable de simuler électroniquement le décollement turbulent ?